

ORIGINAL RESEARCH

Open Access

Incorporating location, routing, and inventory decisions in a bi-objective supply chain design problem with risk-pooling

Reza Tavakkoli-Moghaddam^{1*}, Fateme Forouzanfar² and Sadoullah Ebrahimnejad³

Abstract

This paper considers a single-sourcing network design problem for a three-level supply chain. For the first time, a novel mathematical model is presented considering risk-pooling, the inventory existence at distribution centers (DCs) under demand uncertainty, the existence of several alternatives to transport the product between facilities, and routing of vehicles from distribution centers to customer in a stochastic supply chain system, simultaneously. This problem is formulated as a bi-objective stochastic mixed-integer nonlinear programming model. The aim of this model is to determine the number of located distribution centers, their locations, and capacity levels, and allocating customers to distribution centers and distribution centers to suppliers. It also determines the inventory control decisions on the amount of ordered products and the amount of safety stocks at each opened DC, selecting a type of vehicle for transportation. Moreover, it determines routing decisions, such as determination of vehicles' routes starting from an opened distribution center to serve its allocated customers and returning to that distribution center. All are done in a way that the total system cost and the total transportation time are minimized. The Lingo software is used to solve the presented model. The computational results are illustrated in this paper.

Keywords: Stochastic supply chain; Inventory control; Risk-pooling; Uncertainty; Capacity levels

Background

Nowadays, rapid economic changes and competitive pressure in the global market make companies pay more attention on supply chain topics. The company whose supply chain network structure is more appropriate has higher competitive advantage. This structure helps to overcome environmental disturbances (Dullaert et al. 2007). Analyzing location issues and decision making about facility location is considered as one of the important issues of decision making in companies. Certainly, appropriate facility location has high effects on economic benefits, appropriate service, and customer's satisfaction. Propounding the supply chain because of its effect on factors of operational efficiency, such as inventory, response, and lead time, specific attention is focused on how to create a distribution network. Facility location and how to relate them with customers are an

important factor in designing a distribution network (Francis et al. 1992; Gong et al. 1997).

As nowadays living conditions have changed due to increasing world changes, mutually, situations have changed where supply chains are confronted with and influenced by them. The manager is confronted with more unknown conditions and new risks. Customers' demands have been more uncertain and various, and the lead time on their services is very effective. The demand variety can be recognized as one of the important sources of uncertainty in a supply chain (Gupta et al. 2000). Hence, inventory and product holding in a distribution center are an important issue in the supply chain (Liao et al. 2010). The inventory existence in these centers can lead to a great success in reaching the risk-pooling advantage in order to overcome the variability of customer demands. The proposed risk-pooling strategy and centralizing the inventory at distribution centers are considered as one of the effective ways to manage such a demand uncertainty to achieve appropriate service levels to customers. The lead time is one of the effective

* Correspondence: tavakoli@ut.ac.ir

¹School of Industrial & Systems Engineering and Department of Engineering Science, College of Engineering, University of Tehran, Tehran, Iran
Full list of author information is available at the end of the article

factors in safety stock levels due to customer demand uncertainty (Park et al. 2010). For sure, whether the amount of the level is low for the product, it is considered an additional value that one can gain a long-term or short-term competitive advantage in the market.

The lead time is dependent on different factors, such as transportation mode. Different modes of transportation include a reverse relation between cost and time. It contains different routes for any type of vehicles (Cardona-Valdés et al. 2011). The implicit assumption is that a faster transportation mode is also the more expensive one, creating a trade-off between cost and time affecting the distribution network configuration. In the recent decades, the topic of multi-depot heterogeneous vehicle routing problem is presented in order to increase the productivity and efficiency of transportation systems, in which this model leads to the least cost function by minimizing the number of vehicles (Bettinelli et al. 2011).

Literature review

One of the important factors of the total productivity and profitability of a supply chain is to consider its distribution network, which can be used to achieve variety of the supply chain objectives. Designing a distribution network consists of three subproblems, namely, location allocation, vehicle routing, and inventory control. In the literature, there are some research studies amalgamating two of the above subproblems, such as location-routing problems, inventory-routing problems, and location-inventory problems. These three subproblems of a distribution network design are considered in few papers simultaneously. Location-routing problems are surveyed and classified by Min et al. (1998) and Nagy and Salhi (2007). Inventory-routing problems are studied in several studies (Zhao et al. 2008; Yu et al. 2008; Oppen and Loketangen 2008; Day et al. 2009). In addition, a number of studies have considered location-inventory problems (Daskin et al. 2002; Shen 2005). Finally, Ahmadi Javid and Azad (2010) presented a new model for a location-routing-inventory problem. They considered one objective for their model and did not consider transportation time and risk-pooling. However, in this paper, we present a multi-objective model to concurrently optimize location, allocation, capacity, inventory, selection of vehicles, and routing decisions with risk-pooling in a stochastic supply chain system for the first time. These decisions are made in a way that the total system cost and the total transportation time are minimized.

Problem formulation

Problem description

The trade-off between cost and time creates a bi-objective problem. One criterion tries to minimize the

fixed cost of locating the opened distribution centers, the safety stock costs of distribution center by considering uncertainty in customer's demand, inventory ordering and holding costs, the transportation costs from a plant to its allocated distribution centers, and also vehicle routing costs beginning from a distribution center (DC) with the aim of replying to and covering the devoted customer's demands to the DC by considering risk-pooling. The other criterion looks for the reduction of the time to transport the product along the supply chain. It is desired to minimize the transportation time from a plant to customers. The important assumptions in this paper are as follows:

1. One kind of product is involved (Paksoy and Chang 2010).
2. Each distribution center j is assumed to follow the (Q_j, R_j) inventory policy (Ahmadi Javid and Azad 2010).
3. The inventory control is to be conducted only at DCs in this paper (Park et al. 2010; Ahmadi Javid and Azad 2010).
4. A single-sourcing strategy is considered in the whole supply chain (Park et al. 2010).
5. It is considered that the customers' demands after reaching the retailer are independent and follows a normal distribution (Park et al. 2010; Ahmadi Javid and Azad 2010).
6. Each plant has a limited capacity (Cardona-Valdés et al. 2011).
7. We consider different capacity levels for each distribution center, and finally, one capacity for each of them is selected (Ahmadi Javid and Azad 2010).
8. Each DC with the limited capacity carries on-hand inventory to satisfy demands from customer demand zones as well as safety stock to deal with the mutability of the customer demands at customer demand zones to attain risk-pooling profits (Park et al. 2010).
9. All customers should be served.
10. The number of available vehicles for each type and the number of allowed routes for each DC are limited (Bettinelli et al. 2011).
11. There are several modes of transportation between two consecutive levels.
12. Between two nodes on an echelon, only one type of vehicle is used.
13. A faster transportation mode is the more expensive one (Cardona-Valdés et al. 2011).
14. The amount of products is transported from each plant to each distribution center that is associated with it, and an equal amount of products has been ordered from the desired distribution center to that plant.

15. To determine all feasible routes, the following factors are taken into account:

- Each customer should be visited by only one vehicle.
- Each route begins at a DC and ends at the same DC.
- The sum of the demands of the customers served in each route must not exceed the capacity of the associated vehicle.
- Each of the distribution center and the vehicle have various limited, and determined capacity (Bettinelli et al. 2011; Marinakis and Marinaki 2010).

Model formulation

Following are the notations introduced for the mathematical description of the proposed model.

1. Indices

- (a) I , set of plants indexed by i
- (b) J , set of candidate DC locations indexed by j
- (c) K , set of customer demand zones indexed by k
- (d) N_j , set of capacity levels available to DC_j ($j \in J$)
- (e) Ω_{jl_2} , set of all feasible routes using a vehicle of type l_2 from DC_j ($j \in J$)
- (f) LP_{ij} , set of vehicles l_1 between nodes i and j
- (g) LW_{jk} , set of vehicles l_2 between nodes j and k

2. Parameters

- (a) F_j^n , yearly fixed cost for opening and operating distribution center j with capacity level n ($\forall n \in N_j, \forall j \in J$)
- (b) CP_{ijl_1} , cost of transporting one unit of product from plant i to distribution center j using vehicle l_1
- (c) CW_{rl_2} , cost of sending one unit of product in route r using vehicle l_2 (These costs include the fixed cost of vehicle plus the transportation cost of each demand unit in route r . The mentioned transportation cost for each demand unit is not related to customer demand zone, and it is considered fixed for all locations in each route r .)
- (d) TP_{ijl_1} , time for transporting any quantity of a product from plant i to DC_j using vehicle l_1
- (e) TW_{jl_2r} , time for transporting any quantity of a product from DC_j on route r using vehicle l_2
- (f) λ_j , safety stock factor of DC_j ($j \in J$)
- (g) h_j , unit inventory holding cost at DC_j ($j \in J$), (annually)
- (h) μ_k , mean demand at customer demand zone k
- (i) δ_k^2 , variance of demand at customer demand zone k
- (j) E_j , fixed inventory ordering cost at DC_j
- (k) b_j^n , capacity with level n for DC_j
- (l) MP_i , capacity of plant i
- (l) ω_{l_2} , number of available vehicles of each type l_2
- (n) g_j , number of routes associated with each distribution center j

3. Binary coefficients

- (a) P_{kr} , 1 if and only if customer k is visited by route r , and 0 otherwise

4. Decision variables

- (a) U_j^n , 1 if distribution center j is opened with capacity level n , and 0 otherwise
- (b) A_{ijl_1} , binary variable equal to 1 if vehicle l_1 connecting plant i and DC_j is used, and equal to 0 otherwise
- (c) B_{jkl_2} , binary variable equal to 1 if vehicle l_2 connecting DC_j and customer k is used, and equal to 0 otherwise
- (d) X_r , 1 if and only if route r is selected, and 0 otherwise
- (e) X_{ijl_1} , quantity transported from plant i to DC_j using vehicle l_1

5. Mathematical model

- (a) The problem formulation is as follows:

$$\begin{aligned} \min f_1 = & \sum_{n \in N_j} \sum_{j \in J} F_j^n U_j^n + \sum_{i \in I} \sum_{j \in J} \sum_{l_1 \in LP_{ij}} CP_{ijl_1} A_{ijl_1} X_{ijl_1} \\ & + \sum_{j \in J} \sum_{k \in K} \sum_{l_2 \in LW_{jk}} \sum_{r \in \Omega_{jl_2}} CW_{rl_2} \mu_k P_{kr} X_r \\ & + \sum_{i \in I} \sum_{j \in J} \sum_{k \in K} \sum_{l_1 \in LP_{ij}} \sum_{l_2 \in LW_{jk}} \frac{E_j B_{jkl_2} \mu_k}{X_{ijl_1} A_{ijl_1}} \\ & + \sum_{i \in I} \sum_{j \in J} \sum_{l_1 \in LP_{ij}} \frac{A_{ijl_1} X_{ijl_1} h_j}{2} \\ & + \sum_{j \in J} \lambda_j h_j \sqrt{\sum_{i \in I} \sum_{k \in K} \sum_{l_1 \in LP_{ij}} \sum_{l_2 \in LW_{jk}} \delta_k^2 B_{jkl_2} L_{jil_1} A_{ijl_1}} \end{aligned}$$

$$\min f_2 = \max_j \left(\max_{i, l_1} (TP_{ijl_1} A_{ijl_1}) + \max_{r, l_2} (TW_{jl_2r} X_r) \right)$$

s.t.

$$\sum_{n \in N_j} U_j^n \leq 1 \quad \forall j \in J \quad (1)$$

$$\sum_{k \in K} \sum_{l_2 \in LW_{jk}} \mu_k B_{jkl_2} \leq \sum_{n \in N_j} b_j^n U_j^n \quad \forall j \in J \quad (2)$$

Table 1 U_j^n is 1 if distribution center j is opened with capacity level n . and 0 otherwise

	DC1		DC2	
	Capacity 1	Capacity 2	Capacity 1	Capacity 2
Example 1	1	0	0	1
Example 2	0	1	1	0
Example 3	0	1	1	0
Example 4	1	0	0	1
Example 5	0	1	1	0

Table 2 X_r is 1 if and only if route r is selected, and 0 otherwise

	Route 1		Route 2		Route 3		Route 4		Route 5		Route 6	
	Truck	Airplane	Truck	Airplane	Truck	Airplane	Truck	Airplane	Truck	Airplane	Truck	Airplane
Example 1	1	0	0	1	0	0	0	0	-	-	-	-
Example 2	0	0	0	0	0	1	0	1	-	-	-	-
Example 3	0	0	0	0	0	0	0	0	0	1	0	1
Example 4	0	0	0	0	1	0	1	0	0	0	0	0
Example 5	1	0	1	0	0	0	0	0	-	-	-	-

$$\sum_{i \in I} \sum_{l_1 \in LP_{ij}} X_{ijl_1} + \lambda_j \sqrt{\sum_{i \in I} \sum_{k \in K} \sum_{l_1 \in LP_{ij}} \sum_{l_2 \in LW_{jk}} \delta_k^2 B_{ikl_2} L_{jil_1} A_{ijl_1}} \leq \sum_{n \in N_j} b_j^n U_j^n \forall j \in J \quad (3)$$

$$\sum_{j \in J} \sum_{r \in \Omega_{jl_2}} X_r \leq W_{l_2} \forall l_2 \in LW_{jk} \quad (12)$$

$$\sum_{l_2 \in LW_{jk}} \sum_{r \in \Omega_{jl_2}} X_r \leq g_j \forall j \in J \quad (13)$$

$$\sum_{j \in J} \sum_{l_1 \in LP_{ij}} X_{ijl_1} \leq MP_i \forall i \in I \quad (4)$$

$$X_{ijl_1} - A_{ijl_1} \geq 0 \forall i \in I, \forall j \in J, \forall l_1 \in LP_{ij} \quad (14)$$

$$\sum_{i \in I} \sum_{l_1 \in LP_{ij}} A_{ijl_1} \geq \sum_{n \in N_j} U_j^n \forall j \in J \quad (5)$$

$$\mu_k \geq \sum_{l_2 \in LW_{jk}} \sum_{n \in N_j} \sum_{j \in J} B_{jkl_2} U_j^n \forall k \in K \quad (15)$$

$$\sum_{j \in J} \sum_{l_2 \in LW_{jk}} B_{jkl_2} = 1 \forall k \in K \quad (6)$$

$$MP_i - A_{ijl_1} X_{ijl_1} \geq 0 \forall i \in I, \forall j \in J, \forall l_1 \in LP_{ij} \quad (16)$$

$$\sum_{l_2 \in LW_{jk}} B_{jkl_2} \leq 1 \forall j \in J, \forall k \in K \quad (7)$$

$$U_j^n \in \{0, 1\} \forall j \in J, \forall n \in N_j \quad (17)$$

$$\sum_{l_1 \in LP_{ij}} A_{ijl_1} \leq 1 \forall i \in I, \forall j \in J \quad (8)$$

$$X_r \in \{0, 1\} \forall r \in \bigcup_{j \in J, l_2 \in LW_{jk}} \Omega_{jl_2} \quad (18)$$

$$\sum_{l_1 \in LP_{ij}} \sum_{i \in I} A_{ijl_1} \geq \sum_{l_2 \in LW_{jk}} B_{jkl_2} \forall j \in J, \forall k \in K \quad (9)$$

$$A_{ijl_1} \in \{0, 1\} \forall i \in I, \forall j \in J, \forall l_1 \in LP_{ij} \quad (19)$$

$$\sum_{n \in N_j} U_j^n \geq \sum_{l_2 \in LW_{jk}} B_{jkl_2} \forall j \in J, \forall k \in K \quad (10)$$

$$B_{jkl_2} \in \{0, 1\} \forall j \in J, \forall k \in K, \forall l_2 \in LW_{jk} \quad (20)$$

$$\sum_{j \in J} \sum_{l_2 \in LW_{jk}} \sum_{r \in \Omega_{jl_2}} P_{kr} X_r \geq 1 \forall k \in K \quad (11)$$

In this model, the first objective function minimizes the total expected costs consisting of the fixed cost for

Table 3 A_{ijl_1} , binary variable, where it is 1 if vehicle l_1 connecting plant i and DC $_j$ is used

	Plant 1				Plant 2			
	DC1		DC2		DC1		DC2	
	Train	Airplane	Train	Airplane	Train	Airplane	Train	Airplane
Example 1	1	0	0	0	0	0	1	0
Example 2	0	0	1	0	1	0	0	0
Example 3	0	1	0	0	0	0	0	1
Example 4	1	0	0	1	0	0	0	0
Example 5	0	0	0	0	1	0	0	1

Table 4 B_{jkl_2} binary variable, where it is 1 if vehicle l_2 connecting DC_j and customer k is used

	DC1						DC2					
	Demand 1		Demand 2		Demand 3		Demand 1		Demand 2		Demand 3	
	Truck	Airplane	Truck	Airplane	Truck	Airplane	Truck	Airplane	Truck	Airplane	Truck	Airplane
Example 1	0	0	1	0	1	0	0	1	0	0	0	0
Example 2	0	1	0	1	0	0	0	0	0	0	0	1
Example 3	0	1	0	0	0	0	0	0	0	1	0	1
Example 4	1	0	0	0	1	0	0	0	1	0	0	0
Example 5	1	0	1	0	0	0	0	0	0	0	1	0

opening distribution centers with a certain capacity level, transportation costs from plants to distribution centers, annual routing costs between distribution centers and customer demand zones, and expected annual inventory costs. The second objective function looks for the minimum time to transport the product along any path from the plants to the customers.

Constraint (1) ensures that each distribution center can be assigned to only one capacity level. Constraints (2) and (3) are the capacity constraints associated with the distribution centers, and also, constraint (4) is the capacity constraints associated with the plants. Constraint (5) states that if distribution center j with n capacity is opened, it is serviced by a plant. Constraint (6) represents the single-sourcing constraints for each customer demand zone. Constraints (7) and (8) ensure that if two nodes on an echelon are related to each other, one type of vehicle transports products between them. Constraint (9) makes sure that if the distribution center j gives the service to the customer k , that center must get services at least from a plant. Constraint (10) ensures that if the distribution center j is allocated to customer k by vehicle l_2 , that center should certainly be established with a determined capacity level. Constraint (11) is the standard set covering constraints, modeling assumption 9. Constraints (12) and (13) impose limits on the maximum number of available vehicles of each type and the maximum number of allowed routes for each DC, modeling assumption 10. Constraint (14) makes sure that if plant i gives the service to the DC_j , the amount of

transported products from that plant to the desired distribution center would be more than one. Constraint (15) implies that customers' demands of zone k are more than 1. Constraint (16) is the capacity constraint associated with plant i . Constraints (17) to (20) enforce the integrality restrictions on the binary variables. Finally, constraint (21) enforces the non-negativity restrictions on the other decision variables.

Solution method

Optimization is a mathematical procedure to determine devoting the optimal allocation to scarce resources, and it helps to get the best result from the model solution. In this paper, we consider five examples, and then they are solved by the Lingo 9.0 software to show that this model works well. This software is a comprehensive tool designed to make building and solving linear, nonlinear, and integer optimization models faster, easier, and more efficient. It provides a completely integrated package that includes a powerful language for expressing optimization models, a full featured environment for building and editing problems, and a set of fast built-in solvers. Objective functions (f_i) have been normalized between zero and one. In other words, they have been without any dimension (i.e., scaleless). By using the following formula, these objectives are converted to a single objective function, where f_1' and f_2' are the normalized forms of f_1 and f_2 objective functions.

Table 5 X_{iji} , quantity transported from plant i to DC_j using vehicle l_1

	Plant 1				Plant 2			
	DC1		DC2		DC1		DC2	
	Train	Airplane	Train	Airplane	Train	Airplane	Train	Airplane
Example 1	4	0	0	0	0	0	1	0
Example 2	0	0	2	0	8	0	0	0
Example 3	0	6	0	0	0	0	0	2
Example 4	5	0	0	6	0	0	0	0
Example 5	0	0	0	0	6	0	0	1

$$\min f = \alpha f_1' + (1-\alpha)f_2'$$

To minimize deviations from the ideal, this function is reduced. As the first objective function (f_1) is more important than the second objective function (f_2) in the given problem, the coefficients of the above formula are considered in the form of $\alpha = 0.7$ and $1 - \alpha = 0.3$.

This problem is implemented by this software, and a global optimal solution is obtained. The computational results are shown in Tables 1, 2, 3, 4, and 5.

Conclusions

In this paper, a new mathematical model to design a three-level supply chain has been presented by considering the inventory under uncertain demands, risk-pooling, vehicle routing, transportation time, and cost. The decision related to the transportation options has an impact on the transportation time from plants to customers. The trade-off between cost and time is considered in the formulation of a mathematical model that minimizes both criteria. Therefore, this model holding two objectives has been formulated for the first time as a location-inventory-routing problem with a risk-pooling strategy in a three-level supply chain. The Lingo software has been used to solve the given problem. Some future studies are as follows: considering each parameter as a fuzzy, multi-period planning and solving the presented model by using heuristic or meta-heuristic algorithms.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

RTM managed the study and was responsible for integrating and revising the manuscript. FF contributed to the development of goals, designed the mathematical model, and drafted the manuscript. SE solved the presented model. All authors read and approved the final manuscript.

Acknowledgements

The authors would like to thank autonomous reviewers for their valuable comments that improve the quality and presentation of this paper.

Author details

¹School of Industrial & Systems Engineering and Department of Engineering Science, College of Engineering, University of Tehran, Tehran, Iran. ²School of Industrial Engineering, South Tehran Branch, Islamic Azad University, Tehran, Iran. ³Department of Industrial Engineering, Karaj Branch, Islamic Azad University, Karaj, Iran.

Received: 15 March 2013 Accepted: 19 March 2013
Published: 15 July 2013

References

- Ahmadi Javid A, Azad N (2010) Incorporating location, routing and inventory decisions in supply chain network design. *Transport Res E Logist Transport Rev* 46:582–597
- Bettinelli A, Ceselli A, Righini G (2011) A branch-and-cut-and-price algorithm for the multi-depot heterogeneous vehicle routing problem with time windows. *Transport Res C Emerg Tech* 19:723–740
- Cardona-Valdés Y, Álvarez A, Ozdemir D (2011) A bi-objective supply chain design problem with uncertainty. *Transport Res C Emerg Tech* 19(5):821–832

- Daskin M, Coullard C, Shen ZJ (2002) An inventory–location model: formulation, solution algorithm and computational results. *Ann Oper Res* 110:83–106
- Day JM, Wright PD, Schoenher T, Venkataramanan M, Gaudette K (2009) Improving routing and scheduling decisions at a distributor of industrial gasses. *Omega* 37:227–237
- Dullaert W, Braysy O, Goetschalckx M, Raa B (2007) Supply chain (re)design: support for managerial and policy decisions. *Eur J Transport Infrastruct Res* 7(2):73–91
- Francis RL Jr, McGinnis LF, White JA (1992) Facility layout and location: an analytical approach, 2nd edn. Prentice-Hall, Englewood Cliffs
- Gong D, Gen M, Yamazaki G, Xu W (1997) Hybrid evolutionary method for capacitated location-allocation problem. *Comput Ind Eng* 33:577–580
- Gupta A, Maranas CD, McDonald CM (2000) Mid-term supply chain planning under demand uncertainty: customer demand satisfaction and inventory management. *Comput Chem Eng* 24:2613–2621
- Liao CJ, Lin Y, Shih SC (2010) Vehicle routing with cross-docking in the supply chain. *Expert Syst Appl* 37:6868–6873
- Marinakis Y, Marinaki M (2010) A hybrid genetic-particle swarm optimization algorithm for the vehicle routing problem. *Expert Syst Appl* 37:1446–1455
- Min H, Jayaraman V, Srivastava R (1998) Combined location–routing problems: a synthesis and future research directions. *Eur J Oper Res* 108:1–15
- Nagy G, Salhi S (2007) Location–routing, issues, models, and methods: a review. *Eur J Oper Res* 117:649–672
- Oppen J, Loketangen A (2008) A tabu search approach for the livestock collection problem. *Comput Oper Res* 35:3213–3229
- Paksoy T, Chang C-T (2010) Revised multi-choice goal programming for multi-period, multi-stage inventory controlled supply chain model with popup stores in guerrilla marketing. *Appl Math Model* 34:3586–3598
- Park S, Lee T-E, Sup Sung C (2010) A three-level supply chain network design model with risk-pooling and lead times. *Transport Res E Logist Transport Rev* 46:563–581
- Shen ZJ (2005) A multi-commodity supply chain design problem. *IIE Transactions* 37:753–762
- Yu Y, Chen H, Chu F (2008) A new model and hybrid approach for large scale inventory routing problems. *Eur J Oper Res* 189:1022–1040
- Zhao Q, Chen S, Zhang C (2008) Model and algorithm for inventory/routing decision in a three-echelon logistics system. *Eur J Oper Res* 191:623–635

doi:10.1186/2251-712X-9-19

Cite this article as: Tavakkoli-Moghaddam et al.: Incorporating location, routing, and inventory decisions in a bi-objective supply chain design problem with risk-pooling. *Journal of Industrial Engineering International* 2013 9:19.

Submit your manuscript to a SpringerOpen® journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► springeropen.com