On the monotonicity of generalized barycentric coordinates on convex polygons ☆

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A B S T R A C T

We show that four well-known kinds of generalized barycentric coordinates in convex polygons share a simple monotonicity property: the coordinate function associated with a vertex is increasing along any line from the polygon boundary to that vertex. This shows that the coordinate functions have no local extrema and that their contours are single curves connecting pairs of points on the two edges adjacent to the vertex.

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1. Introduction

Let $P \subset \mathbb{R}^2$ be a convex polygon, with vertices $\mathbf{v}_1, \mathbf{v}_2, \ldots, \mathbf{v}_n$, $n \geq 3$, in some anticlockwise ordering. Fig. 1 shows an example with $n = 5$. Any functions $\phi_i : P \to \mathbb{R}$, $i = 1, \ldots, n$, are *generalized barycentric coordinates* (GBCs) if, for all $\mathbf{x} \in P$, $\phi_i(\mathbf{x}) \geq 0$, $i = 1, \ldots, n$, and

$$\sum_{i=1}^{n} \phi_i(\mathbf{x}) = 1, \qquad \sum_{i=1}^{n} \phi_i(\mathbf{x})\mathbf{v}_i = \mathbf{x}. \tag{1}$$

From this definition one can show that all GBCs have the same values on the boundary of the polygon, ∂P. Specifically, $\phi_i|_{\partial P} = f_i$, where the boundary function $f_i : \partial P \to \mathbb{R}$ has the values

$$f_i|_{e_j} = 0, \qquad j \neq i-1, 1,$$
$$f_i((1-\mu)\mathbf{v}_{i\pm 1} + \mu\mathbf{v}_i) = \mu, \qquad \mu \in [0, 1], \tag{2}$$

and e_j is the j-th edge, $e_j := [\mathbf{v}_j, \mathbf{v}_{j+1}]$. Here and throughout, vertices, edges, and so on are indexed cyclically, i.e., $\mathbf{v}_{n+1} := \mathbf{v}_1$ etc.

We can see that ϕ_i is increasing along the edges e_{i-1} and e_i in the direction towards $\mathbf{v}_i$. In this note we show that several well known GBCs share a more general monotonicity property. We will say that $\phi_1, \ldots, \phi_n$ are *monotonic* if, for all

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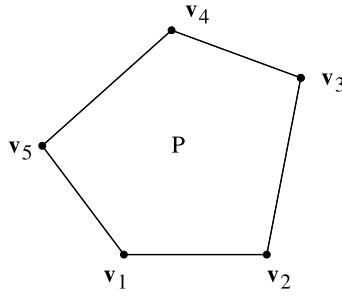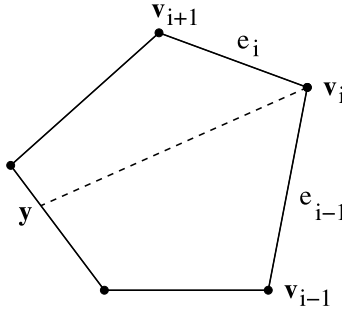   *E-mail address:* michaelf@math.uio.no.

Fig. 1. Convex polygon.

Fig. 2. Line segment connecting a boundary point $\mathbf{y}$ to $\mathbf{v}_i$.

$i = 1, \ldots, n$, and for all $\mathbf{y} \in \partial P$, $\mathbf{y} \neq \mathbf{v}_i$, the coordinate ϕ_i is increasing along the line segment from $\mathbf{y}$ to $\mathbf{v}_i$. Fig. 2 shows an example. Thus, by monotonic we mean that if

$$\mathbf{x} = (1 - \lambda)\mathbf{y} + \lambda\mathbf{v}_i \qquad \text{and} \qquad \tilde{\mathbf{x}} = (1 - \tilde{\lambda})\mathbf{y} + \tilde{\lambda}\mathbf{v}_i, \tag{3}$$

with $0 < \lambda < \tilde{\lambda} < 1$, then $\phi_i(\mathbf{x}) < \phi_i(\tilde{\mathbf{x}})$, and we need only check this property for boundary points $\mathbf{y} \notin e_{i-1}, e_i$. We will show that four distinct kinds of GBCs are monotonic: Wachspress coordinates, harmonic coordinates, Gordon–Wixom coordinates, and mean value coordinates.

Monotonicity does not follow from the definition (1) alone, since it is local to each point $\mathbf{x}$. We could construct an example of 'strange' GBCs that are neither continuous nor monotonic. If both coordinates of $\mathbf{x}$ are rational numbers, let $\phi_1(\mathbf{x}), \ldots, \phi_n(\mathbf{x})$ be the Wachspress coordinates of $\mathbf{x}$. Otherwise, if either coordinate is non-rational, let $\phi_1(\mathbf{x}), \ldots, \phi_n(\mathbf{x})$ be the mean value coordinates of $\mathbf{x}$. This defines a set of GBCs $\phi_1, \ldots, \phi_n$ for all $\mathbf{x}$ in P that are clearly not continuous (except on the boundary of P), and clearly not monotonic either.

The monotonicity property shows that each contour of ϕ_i is a single curve connecting a point on the edge e_{i-1} to the corresponding point on the edge e_i. Despite the fact that numerous contour plots of GBCs have appeared in the literature over several years, and they tend to exhibit this behavior, a mathematical proof seems to be missing. Another consequence of monotonicity is that ϕ_i cannot have any extrema in P.

It seems reasonable to use the simple term 'monotonic' because (a) this is the property that ϕ_i has along each line passing through $\mathbf{v}_i$ and (b) it seems unlikely that ϕ_i will be monotonic, in general, along any other line. Certainly, if we take any two points $\mathbf{y}_1$ and $\mathbf{y}_2$ on the boundary of P that lie on distinct edges other than e_i and e_{i-1}, then $\phi_i(\mathbf{y}_1) = \phi_i(\mathbf{y}_2) = 0$ and ϕ_i is positive on the line between $\mathbf{y}_1$ and $\mathbf{y}_2$, from which we conclude that ϕ_i is not monotonic on that line.

2. Wachspress' rational coordinates

To define Wachspress' coordinates (Wachspress, 1975; Warren, 1996; Meyer et al., 2002; Warren et al., 2007), let $\mathbf{n}_j$ denote the outward unit normal to the edge e_j, and for $\mathbf{x} \in P$, let $h_j(\mathbf{x})$ be the perpendicular distance of $\mathbf{x}$ to e_j, i.e., by the scalar product,

$$h_j(\mathbf{x}) = (\mathbf{v}_j - \mathbf{x}) \cdot \mathbf{n}_j = (\mathbf{v}_{j+1} - \mathbf{x}) \cdot \mathbf{n}_j. \tag{4}$$

Then the i-th Wachspress coordinate is $\phi_i = w_i/W$, where

$$w_i(\mathbf{x}) = \frac{c_i}{h_{i-1}(\mathbf{x})h_i(\mathbf{x})}, \qquad c_i = \mathbf{n}_{i-1} \times \mathbf{n}_i, \qquad W = \sum_{j=1}^{n} w_j,$$

and $\times$ is the scalar-valued cross product, so $\mathbf{n}_{i-1} \times \mathbf{n}_i = \det[\mathbf{n}_{i-1}, \mathbf{n}_i]$.

To derive the monotonicity property consider the gradient $\nabla\phi_i$ of ϕ_i for some fixed i. By the quotient rule,

$$\nabla\phi_i = \frac{1}{W^2}\left(W\nabla w_i - w_i\nabla W\right) = \frac{w_i}{W^2}\sum_{j=1}^{n} w_j(\mathbf{R}_i - \mathbf{R}_j),$$

where $\mathbf{R}_j := \nabla w_j / w_j$. Therefore, the directional derivative of ϕ_i in the (not necessarily unit) direction $\mathbf{v}_i - \mathbf{x}$ is

$$D_{\mathbf{v}_i-\mathbf{x}}\phi_i(\mathbf{x}) = (\mathbf{v}_i - \mathbf{x}) \cdot \nabla\phi_i(\mathbf{x}) = \frac{w_i(\mathbf{x})}{W^2(\mathbf{x})}\sum_{j\neq i} w_j(\mathbf{x})(a_{ii}(\mathbf{x}) - a_{ij}(\mathbf{x})),$$

where

$$a_{ij}(\mathbf{x}) := (\mathbf{v}_i - \mathbf{x}) \cdot \mathbf{R}_j(\mathbf{x}).$$

Thus to show that $D_{\mathbf{v}_i-\mathbf{x}}\phi_i(\mathbf{x}) > 0$, and since $w_k(\mathbf{x}) > 0$ for all k, it is sufficient to show that

$$a_{ii}(\mathbf{x}) > a_{ij}(\mathbf{x}), \qquad j \neq i. \tag{5}$$

Since $\nabla h_j = -\mathbf{n}_j$, we find

$$\nabla w_j(\mathbf{x}) = \left(\frac{\mathbf{n}_{j-1}}{h_{j-1}(\mathbf{x})} + \frac{\mathbf{n}_j}{h_j(\mathbf{x})}\right) w_j(\mathbf{x}),$$

and so

$$\mathbf{R}_j(\mathbf{x}) = \frac{\mathbf{n}_{j-1}}{h_{j-1}(\mathbf{x})} + \frac{\mathbf{n}_j}{h_j(\mathbf{x})},$$

as shown in Floater et al. (2014). Now observe that for any $k = 1, \ldots, n$,

$$(\mathbf{v}_i - \mathbf{x}) \cdot \mathbf{n}_k = (\mathbf{v}_k - \mathbf{x}) \cdot \mathbf{n}_k - (\mathbf{v}_k - \mathbf{v}_i) \cdot \mathbf{n}_k = h_k(\mathbf{x}) - h_k(\mathbf{v}_i),$$

and therefore, for any $j = 1, \ldots, n$,

$$a_{ij}(\mathbf{x}) = 2 - \frac{h_{j-1}(\mathbf{v}_i)}{h_{j-1}(\mathbf{x})} - \frac{h_j(\mathbf{v}_i)}{h_j(\mathbf{x})}.$$

It follows that $a_{ii}(\mathbf{x}) = 2$ and $a_{ij}(\mathbf{x}) < 2$, $j \neq i$, which implies (5).

3. Harmonic coordinates

The harmonic coordinates (Floater et al., 2006; Joshi et al., 2007) are defined by the Laplace equation with Dirichlet boundary condition:

$$\Delta\phi_i = 0, \quad \text{in } P,$$
$$\phi_i = f_i, \quad \text{on } \partial P.$$

Here, Δ is the Laplace operator, $\partial^2/\partial x^2 + \partial^2/\partial y^2$, where $\mathbf{x} = (x, y)$.

To show monotonicity, it is sufficient to show that $\psi_i > 0$ in the interior of P, where

$$\psi_i(\mathbf{x}) := D_{\mathbf{v}_i-\mathbf{x}}\phi_i(\mathbf{x}) = (\mathbf{v}_i - \mathbf{x}) \cdot \nabla\phi_i(\mathbf{x}), \qquad \mathbf{x} \in P.$$

To show this we can use the maximum principle (Protter and Weinberger, 1967) for the Laplace operator. By differentiating ψ_i we find

$$\Delta\psi_i = -2\Delta\phi_i + (\mathbf{v}_i - \mathbf{x}) \cdot \nabla(\Delta\phi_i),$$

and therefore, since ϕ_i is harmonic, so is ψ_i. Considering the boundary values of ψ_i, if $\mathbf{x}$ belongs to $e_{i\pm1}$ then

$$\psi_i(\mathbf{x}) = \frac{|\mathbf{v}_i - \mathbf{x}|}{|\mathbf{v}_{i\pm1} - \mathbf{v}_i|} \geq 0.$$

If, on the other hand, $\mathbf{x}$ belongs to an edge e_j, $j \neq i-1, i$, then, since $\phi_i(\mathbf{x}) = 0$ and $\phi_i \geq 0$ in P, we see that, by the convexity of P, $\psi_i(\mathbf{x}) \geq 0$. Thus $\psi_i \geq 0$ on ∂P. Since $\Delta\psi_i = 0$ in P, and ψ_i cannot be constant, it cannot attain its minimum in the interior of P, and so $\psi_i > 0$ in P.

Fig. 3. Points involved in Gordon–Wixom coordinates.

4. Gordon–Wixom coordinates

To define Gordon–Wixom coordinates (Gordon and Wixom, 1974; Belyaev, 2006; Manson et al., 2011) let $\mathbf{x} \in P$ and for any angle $\theta \in \mathbb{R}$, let $\mathbf{y}_\theta$ be the unique point of intersection between the ray

$$L_\theta := \{\mathbf{x} + s(\cos\theta, \sin\theta) : s \geq 0\} \tag{6}$$

and the polygon boundary ∂P, and let $s_\theta = |\mathbf{y}_\theta - \mathbf{x}|$, the Euclidean distance from $\mathbf{x}$ to $\mathbf{y}_\theta$. The ray $L_{\theta+\pi}$, in the direction opposite to L_θ, also meets ∂P uniquely, at the point $\mathbf{z}_\theta := \mathbf{y}_{\theta+\pi}$, whose distance from $\mathbf{x}$ is $t_\theta := s_{\theta+\pi}$. Then the i-th coordinate at $\mathbf{x}$ is defined as the integral mean of linear interpolants,

$$\phi_i(\mathbf{x}) = \frac{1}{\pi} \int_0^\pi \left(\frac{s_\theta}{t_\theta + s_\theta} f_i(\mathbf{z}_\theta) + \frac{t_\theta}{t_\theta + s_\theta} f_i(\mathbf{y}_\theta) \right) d\theta,$$

or equivalently,

$$\phi_i(\mathbf{x}) = \frac{1}{\pi} \int_0^{2\pi} \frac{t_\theta}{t_\theta + s_\theta} f_i(\mathbf{y}_\theta) \, d\theta. \tag{7}$$

To show monotonicity, suppose that $\mathbf{y}$, $\mathbf{x}$, $\tilde{\mathbf{x}}$, λ, and $\tilde{\lambda}$ are as in (3), and define $\tilde{\mathbf{y}}_\theta$, $\tilde{s}_\theta$, and $\tilde{t}_\theta$ with respect to the point $\tilde{\mathbf{x}}$, in the same way as $\mathbf{y}_\theta$, s_θ, and t_θ are defined with respect to $\mathbf{x}$. Then, from (7), it is sufficient to show that

$$\frac{t_\theta}{t_\theta + s_\theta} f_i(\mathbf{y}_\theta) \leq \frac{\tilde{t}_\theta}{\tilde{t}_\theta + \tilde{s}_\theta} f_i(\tilde{\mathbf{y}}_\theta) \tag{8}$$

for all θ, with strict inequality for at least one θ. Suppose first that $\mathbf{y}_\theta \notin e_{i-1}, e_i$. Then $f_i(\mathbf{y}_\theta) = 0$ and (8) trivially holds. Suppose otherwise that $\mathbf{y}_\theta \in e_j$ for some $j \in \{i-1, i\}$. Referring to Fig. 3, since $\tilde{\lambda} \in [\lambda, 1]$, we have $\tilde{\mathbf{x}} \in [\mathbf{x}, \mathbf{v}_i]$ and $\tilde{\mathbf{y}}_\theta \in [\mathbf{y}_\theta, \mathbf{v}_i]$ and $f_i(\mathbf{y}_\theta) \leq f_i(\tilde{\mathbf{y}}_\theta) \leq 1$.

So $f_i(\mathbf{y}_\theta) \leq f_i(\tilde{\mathbf{y}}_\theta)$ and (8) holds if

$$\frac{t_\theta}{t_\theta + s_\theta} \leq \frac{\tilde{t}_\theta}{\tilde{t}_\theta + \tilde{s}_\theta},$$

or equivalently (by considering the reciprocal),

$$\frac{t_\theta}{s_\theta} \leq \frac{\tilde{t}_\theta}{\tilde{s}_\theta}. \tag{9}$$

The distance $\tilde{s}_\theta$ decreases linearly with $\tilde{\lambda}$ for $\tilde{\lambda} \in [\lambda, 1]$, from s_θ to 0, and so

$$\tilde{s}_\theta = \frac{1 - \tilde{\lambda}}{1 - \lambda} s_\theta. \tag{10}$$

On the other hand, by the convexity of P, the line segment $[\mathbf{z}_\theta, \mathbf{v}_i]$ intersects the line segment $[\tilde{\mathbf{x}}, \tilde{\mathbf{z}}_\theta]$. Let $\mathbf{q}$ be the point of intersection, shown in Fig. 3. Then

$$\tilde{t}_\theta = |\tilde{\mathbf{z}}_\theta - \tilde{\mathbf{x}}| \geq |\mathbf{q} - \tilde{\mathbf{x}}| = \frac{1 - \tilde{\lambda}}{1 - \lambda} t_\theta, \tag{11}$$

which, combined with (10), implies (9). This proves (8). We can also see that if $\mathbf{y}_\theta \in e_j$ for some $j \in \{i-1, i\}$ and $\mathbf{y}_\theta \neq \mathbf{v}_i$ then $f_i(\mathbf{y}_\theta) < f_i(\tilde{\mathbf{y}}_\theta)$ and the inequality in (8) is strict.

5. Mean value coordinates

The i-th mean value coordinate at $\mathbf{x} \in P$ (Floater, 2003) can be defined as the ratio of integrals

$$\phi_i(\mathbf{x}) = \int\limits_0^{2\pi} \frac{f_i(\mathbf{y}_\theta)}{s_\theta} \, d\theta \Big/ \int\limits_0^{2\pi} \frac{1}{s_\alpha} \, d\alpha, \tag{12}$$

with $\mathbf{y}_\theta$ and s_θ as defined in Section 4.

Regarding monotonicity, let $\mathbf{y}$, $\mathbf{x}$, and λ be as in (3). To show that $\phi_i(\mathbf{x})$ is increasing in λ at $\mathbf{x}$ it is sufficient to show that

$$\frac{f_i(\mathbf{y}_\theta)}{s_\theta} \Big/ \int\limits_0^{2\pi} \frac{1}{s_\alpha} \, d\alpha,$$

is non-decreasing in λ for all θ, and increasing for some θ. Then, since the reciprocal of an increasing function is decreasing, and vice versa, a similar consideration of the angle α shows that it is sufficient that

$$\frac{s_\alpha}{s_\theta} f_i(\mathbf{y}_\theta)$$

is non-decreasing for all θ and α, and increasing for at least one choice of θ. Thus it is sufficient to show that with $\tilde{\mathbf{x}}$ also as in (3),

$$\frac{s_\alpha}{s_\theta} f_i(\mathbf{y}_\theta) \leq \frac{\tilde{s}_\alpha}{\tilde{s}_\theta} f_i(\tilde{\mathbf{y}}_\theta) \tag{13}$$

for all θ and α, with strict inequality for some choice of θ.

The proof of (13) is similar to that of (8). If $\mathbf{y}_\theta \notin e_{i-1}, e_i$ then (13) trivially holds because $f_i(\mathbf{y}_\theta) = 0$. Otherwise, with $\mathbf{y}_\theta \in e_j$ for some $j \in \{i-1, i\}$, it is sufficient to show that

$$\frac{s_\alpha}{s_\theta} \leq \frac{\tilde{s}_\alpha}{\tilde{s}_\theta}.$$

This follows from equation (10) and the fact that, in analogy to (11),

$$\tilde{s}_\alpha \geq \frac{1 - \tilde{\lambda}}{1 - \lambda} s_\alpha,$$

with $\mathbf{y}_\alpha$ and $\tilde{\mathbf{y}}_\alpha$ playing the role of $\mathbf{z}_\theta$ and $\tilde{\mathbf{z}}_\theta$, and this establishes (13). Similar to Section 4, if $\mathbf{y}_\theta \in e_j$ for some $j \in \{i-1, i\}$ but with $\mathbf{y}_\theta \neq \mathbf{v}_i$ then $f_i(\mathbf{y}_\theta) < f_i(\tilde{\mathbf{y}}_\theta)$ and the inequality in (13) is strict.

6. Higher dimensions

As one might expect, the monotonicity property studied here extends in the obvious way to convex polyhedra and, more generally, convex polytopes in higher dimensions for the four coordinates considered here, if we make the right definitions.

Considering first Wachspress coordinates, the proof of monotonicity of Section 2 generalizes at least to simple convex polytopes in $\mathbb{R}^d$, i.e., convex polytopes in which every vertex has d adjacent $(d-1)$-dimensional faces. Using the definitions derived in Warren et al. (2007), and applying the notation and gradient formulas of Sec. 2 of Floater et al. (2014), the argument is similar, and inequality (5) now follows from the fact that $a_{ii}(\mathbf{x}) = d$ and $a_{ij}(\mathbf{x}) < d$, $j \neq i$.

For the remaining three kinds of GBCs: harmonic, GW, and MV, we do not need to restrict to a simple polytope, and, moreover, we have a choice of how to generalize the boundary functions f_i of (2). For each $(d-1)$-dimensional face of the convex polytope we could choose any set of GBCs for that face that are themselves monotonic. These face GBCs then define the boundary functions f_i for the vertices $\mathbf{v}_i$ of the polytope. The proof of monotonicity of the harmonic coordinates is now as before, with ψ_i harmonic in P and $\psi_i \geq 0$ on ∂P due to f_i being monotonic on the faces adjacent to $\mathbf{v}_i$. The proof of monotonicity for GW and MV coordinates is also similar to the 2-D case, with integration carried out over unit vectors $\boldsymbol{\mu}$ on the unit sphere in $\mathbb{R}^d$ instead of angles around the unit circle. We would replace the ray L_θ of (6) by

$$L_{\boldsymbol{\mu}} := \{\mathbf{x} + s\boldsymbol{\mu} : s \geq 0\},$$

and could denote by $\mathbf{y}_{\boldsymbol{\mu}}$ its point of intersection with ∂P. Then for any fixed $\boldsymbol{\mu}$, the five points $\mathbf{v}_i$, $\mathbf{x}$, and $\tilde{\mathbf{x}}$ of (3) and $\mathbf{y}_{\boldsymbol{\mu}}$ and $\tilde{\mathbf{y}}_{\boldsymbol{\mu}}$ would all lie in the same plane, and the steps used to prove (8) and (13) are the same.

7. Future work

Monotonicity could also be investigated for other GBCs, such as maximum entropy coordinates (Sukumar, 2004), the families of coordinates of Floater et al. (2006), and the inverse rational bilinear coordinates for quadrilaterals of Floater (2015).

A shape-property related to monotonicity is convexity. Are there GBCs which are convex as well as monotonic along the lines considered here?

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