Autonomic computation offloading in mobile edge for IoT applications

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HIGHLIGHTS

- An autonomic computation offloading model for mobile edge/fog is proposed.
- A deep reinforcement Q-learning model is used for computation offloading.
- Our method significantly improves the performance of the computation offloading.

ABSTRACT

Computation offloading is a protuberant elucidation for the resource-constrained mobile devices to accomplish the process demands high computation capability. The mobile cloud is the well-known existing offloading platform, which usually far-end network solution, to leverage computation of the resource-constrained mobile devices. Because of the far-end network solution, the user devices experience higher latency or network delay, which negatively affects the real-time mobile Internet of things (IoT) applications. Therefore, this paper proposed near-end network solution of computation offloading in mobile edge/fog. The mobility, heterogeneity and geographical distribution mobile devices through several challenges in computation offloading in mobile edge/fog. However, for handling the computation resource demand from the massive mobile devices, a deep Q-learning based autonomic management framework is proposed. The distributed edge/fog network controller (FNC) scavenging the available edge/fog resources i.e. processing, memory, network to enable edge/fog computation service. The randomness in the availability of resources and numerous options for allocating those resources for offloading computation fits the problem appropriate for modeling through Markov decision process (MDP) and solution through reinforcement learning. The proposed model is simulated through MATLAB considering oscillated resource demands and mobility of end user devices. The proposed autonomic deep Q-learning based method significantly improves the performance of the computation offloading through minimizing the latency of service computing. The total power consumption due to different offloading decisions is also studied for comparative study purpose which shows the proposed approach as energy efficient with respect to the state-of-the-art computation offloading solutions.

1. Introduction

The massive growth of mobile devices (e.g. smart phones, laptops, tablet pc’s, mobile IoT’s and automobiles) and their computation demands imposed a huge scarcity in communication network and computation resources. Some of the application services e.g. image processing and real-time translation services require extensive computation, the resource-constrained mobile devices are not the feasible domiciles to process those applications. Therefore, to meet the computation demands of such type of mobile devices and applications the outsourcing of computation is the demand in need.

Computation offloading is a relocation mechanism of processes or modules of software applications or systems from resource-constrained devices to the resource-rich platforms. Mobile cloud is the well-known platform for computation offloading of mobile devices. Mobile cloud computing is becoming a popular method...
for mobile services e.g. mobile video games, video streaming, education, social networking, messenger and mobile healthcare services [1].

However, the key barriers to offloading computation in mobile cloud are the network bandwidth and latency. Data travels a longer hazardous path from mobile device to the mobile cloud during offloading and thus consumes huge network bandwidth [2]. The bandwidth scarcity, and internet bottlenecks and traffic congestions are the catalysts for the higher latency of offloading computation. Real-time applications are highly latency sensitive and thus it requires to compute data in a close proximity of mobile devices or users. So, mobile fog can be the effective and suitable platform for offloading mobile computation.

Fog computing [3] is introduced by Cisco Systems Inc. to extend the cloud computing paradigm to the edge of network especially for Internet of Things (IoT) services. Mobile Fog is the complementary model of fog computing especially prototyped for seamless and latency-aware mobile services [4]. However, the key research questions for offloading computation in mobile fog are (1) How to offload computation in the mobile fog? (2) Which module or process of mobile application should offload? (3) Where to offload the module or process for minimizing the latency of service computing? Moreover, the mobility, heterogeneity and geographical distribution mobile devices impose additional challenges of computation offloading in mobile fog. This research contributes to finding the answer to the above questions. The key contributions of this research are as follows.

- A code offloading framework is proposed for computation offloading in mobile fog environment. The code analyzer unit of the framework determines which basic blocks of the code are computation hungry and subject to offload.
- A deep Q-learning [5] based computation offloading method is proposed for the autonomic management of massive offloading request. The trained code offloader unit of the proposed framework takes the offloading decision considering resource demand, resource availability and network status to minimize the latency of service computing.
- The performance of the proposed model studied through simulation. The performance gain in terms of latency and energy efficiency justifies the dominance of the proposed autonomic offloading model.

Rest of the paper is organized as follows. In Section 2, we discussed the related works. The system model of mobile fog is presented in Section 3. The deep Q-learning based autonomic code offloading method in mobile fog is illustrated in Section 4. We presented the simulation and performance study results in Section 5. Finally, we concluded the paper in Section 6 with some future directions.

2. State-of-the-arts computation offloading methods

Mobile fog interplays with tradition cloud to access its huge computational resources. Thus, this section discussed state-of-the-arts resource provisioning methods of legacy cloud computing paradigm. Afterwards, the pioneer works on computation offloading in the mobile cloud are discussed in this section.

The elasticity and scalability of cloud computing are achieved through virtualization of cloud resources. The resources of cloud data centers are managed through VM configuration and placement methods. The optimized placement of virtual machines in cloud brokering architecture is proposed in [6]. The paper presented very detail architecture of cloud service broker. The optimized selection of virtual resources of cloud brokers through cloud scheduler was one of the primary objectives of the paper. The holistic approach, OPTIMIS, is proposed in [7] to optimize the service lifecycle of cloud service provisioning. The paper introduced a toolkit for reliable, sustainable and trustful service provisioning.

The cost-effective deployment of computing clusters in multi-cloud infrastructure is presented in [8]. They provided analysis on the viewpoint of performance and cost. The proposal is only for loosely coupled many-task computing (MTC) applications. The proposal overlooks tightly coupled MTC applications, where facts are highly interdependent and synchronizing among the computational units is necessary.

The optimal allocation of computing and networking resources in cloud computing networks is proposed in [9]. The authors of this paper used mixed integer programming to formulate optimal networked cloud mapping problem. In the proposal, the authors modeled cloud request as undirected graph of virtual nodes and virtual network links and then allocate QoS-aware virtual resources according to networked cloud request.

Energy-aware resource allocation and provisioning methods are discussed in [10]. They proposed a green cloud architecture with power model, VMs placement and migration algorithm. The proposal is fully devoted to power-aware policy development by minimizing the migration of VMs among multi-cloud infrastructure.

A joint or coordinated VM resource provisioning and maintenance scheduling method is proposed by the authors of [11]. They formulated the problem as an Integer Linear Programming problem and then transformed it into an equivalent problem to obtain linear programming relaxation solution, then they apply LIST rounding algorithm towards a final approximate solution. CoTuner [12] is the model-free reinforcement learning based VM configuration framework. It can configure VM’s on the fly with changing workloads.

In mobile cloud computing, most of the pioneer works proposed the VM migration mechanism in a surrogate cloud server. The cloudlets [13] are the trusted, resource-rich and nearby computing box to offload mobile data for extensive processing. Cloudlet is well-connected to the central cloud through internet and it is considered within one hop communication range of mobile devices. The cloudlets are also called the little clouds, which act as the surrogates of centralized mobile cloud to process latency sensitive application services. The adjacent cloudlets are connected with each other through mesh connectivity [14] and can communicate and migrate virtual machines (VMs) with one other to support mobility. Each cloudlet is connected with centralized mobile cloud to fetch, store, and process necessary data through VM placement. The physical servers of host mobile cloud and cloudlets are placed in the fixed geographical locations but because of the arbitrary user requests and resource requirements the states of VMs change dynamically. The cloudlets are placed usually in coffee shops, subway stations and other public places. The dense deployment of cloudlet requires a huge investment.

CloneCloud [15] proposed a solution of offloading computation in cloud servers by introducing an automatic application partitioner, which portioned the mobile application at runtime and deploys it onto device clones in the computational cloud. The communication latency and VM formation cause jitter in latency sensitive applications. The mobility of mobile users is ubiquitous and thus we need more efficient solutions which ensure seamless mobile services.

MobiCloud [16] proposed the Mobile Ad Hoc Networks (MAN- ANs) as the mobile cloud computing units, where each of the mobile nodes acts like the service node. Every service node is mirrored in virtualized cloud servers to provide secure service architecture. Scavenger [17] is the mobile cyber-foraging system to offload resource intensive jobs. The framework provides an opportunity to offload computation to nearby surrogate devices.
Execution offloading in mobile cloud computing is discussed in [18]. The authors of this paper, proposed an effective way to offload useful heap objects and partial stack in the run-time of application. ThinkAir [19] proposed, a method level computation offloading mechanism for mobile cloud computing. The framework has the capability of dynamic adaptation and dynamic scaling of computational power.

In contrast to above methods, we propose deep reinforcement learning especially deep Q-learning based basic block offloading mechanism in mobile fog. The autonomic management of offloading jobs while ensuring the low latency and energy efficiency in service computing makes this proposal novel in its approach and contribution.

3. System model of mobile fog computing

Mobile Fog is the complementary model of fog computing especially prototyped for seamless and latency-aware mobile services. The system model of the mobile fog is presented in Fig. 1. The presented system model is derived from the hierarchical architecture of LTE (long-term evolution) 3GPP (3rd Generation Partnership Project) and Wi-Fi (wireless-fidelity) internetworking reference model [20].

In this architecture, AP is not only responsible for providing connections between mobile stations (STA) and IP networks but also having sufficient storage, processing, I/O and networking capability to provide mobile cloud services e.g. IaaS, PaaS, and NaaS etc. We consider IEEE 802.11 WLAN interface between STA and AP, and IEEE Ethernet interface between AP and APC.

Similar to the AP, the APC is not only responsible for communication handovers but also responsible for code block migration to support stations mobility in mobile cloud and having sufficient storage, processing, I/O and networking capability to provide mobile cloud services as well. Therefore, the APC are also considered as the fog network controller (FNC). The upward and downward entities are interfaced with IEEE Ethernet interfacing standards. In Fig. 1, the fog enabled AP and APC are symbolized as F-AP and F-APC. The 3GPP AAA (3rd generation partnership project’s authentication, authorization and accounting server) is responsible for global authentication of mobile stations of a mobile fog through EAP—AKA (Extensible authentication protocol—authentication and key agreement) over IKEv2 (Internet key exchange protocol version 2) as obtaining authentication vector from home subscriber server (HSS) unit of LTE network. We assume the Diameter as the AAA protocol in our mobile IP-based networks [21]. The P-GW (Packet data network-gateway) enables packet data network (PDN) access for user equipment’s (UE) or STAs and also responsible for inter ePDG virtual machine (VM) migration in mobile fog computing. Public cloud is the traditional service delivery network of scalable, ubiquitous and pay-as-you-go services which can be accessed through the internet from static and mobile devices. If necessary, the mobile fog can utilize the required everything as a service (XaaS) of public cloud e.g. to leverage computational loads, to process latency-insensitive data, to archive transactional history.
etc. The mobile fog can also interplay with public cloud to deliver cost-effective, ubiquitous and scalable mobile services.

4. Deep Q-learning based autonomic computation offloading

This section discusses the approach of offloading computation in mobile fog based on the system model presented in Section 3. The basic block [22] migration policy is used through mobile agents for offloading code from resource-constrained mobile stations to resource richer mobile fog. The programming code is partitioned into code generation and optimization unit of F-AP and deployed in different F-AP and also in different F-AP. According to the flow graph [22–24] of the generated codes, the basic blocks are executed on various fog nodes, where independent basic blocks are executed in a parallel fashion. To balance loads of different fog nodes, the basic blocks are migrated in different nodes within the same fog or in neighboring (or distant) fog. The communication among the mobile fogs is controlled by the ePDG node but offloading and migration performed through the tunnel between the F-APC nodes to support mobility of the mobile stations. The basic blocks can be migrated through ePDG node in a distant mobile fog for load balancing and load sharing. The basic blocks are synthesized together in case of necessary docker-container deployment in public cloud.

4.1. Code offloading framework

The traditional mobile devices have no built-in framework for offloading computation. Therefore, a middle-ware is required on top of the smart-devices operating system to perform code offloading. The proposed code offloading framework is presented in Fig. 2, where the compiler translates the high level language of applications to machine understandable form. The front end performs syntax and semantic analysis, and also generates intermediate codes. The back end of the compiler generates byte code, groups the independent byte code syntax to form basic blocks and prepares the flow graph from the basic blocks as shown in Fig. 3.

It is assumed that for the first time the application executes on the host smart device to collect the run time statistics through execution analyzer module. The execution analyzer module prepares a table of usage resources and execution time of each basic block as shown in Table 1. The application manager assigns Application ID, Method ID and Block ID of each basic block. The execution manager also keeps the record of average memory usage, CPU utilization and execution duration and also number of times the basic block executes in a single run. Moreover, it also defines a basic block as not offloadable (i.e. set the offloadable flag 0) if the block requires dedicated peripherals from the smart devices (e.g. smart devices camera) during its execution.

The code offloader module is responsible for offloading the codes to nearby Fog nodes. The availability of Fog nodes are realized through network manager. It only offloads the offloadable basic blocks if necessary. If the average CPU and memory utilization of the basic block is less than the available memory and CPU then application manager executes that basic block on the host smart device. Otherwise it determines the expected execution time of host processing (i.e. \( EET_H \)) based on the available memory and CPU of the host smart device. Then it also requests F-APC for the expected execution time of Fog processing (i.e. \( EET_F \)) based on the available memory and CPU and link bandwidths of the mobile Fog by sending the history of CPU and memory usage of hosts while the block processed initially in the host. Then the code offloader compare these two expected execution time results i.e. \( EET_H \) and \( EET_F \) and make the offloading decision if \( EET_F < EET_H \). Additionally, code offloader performs Breadth First Search (BFS) on the flow graph of back end compiler and find out the independent blocks of same depth and offloaded in mobile Fog for parallel execution.

To support the mobility of both mobile stations and Fog nodes, the basic blocks are migrated in different nodes within the same Fog or in neighboring (or distant) Fog. The communication between two mobile fogs is controlled by the ePDG node but offloading and migration performed through the tunnel between the F-APC nodes to support mobility of the mobile stations. The basic
blocks can be migrated through ePDG node in a distant mobile Fog also for load balancing and load sharing purpose.

4.2. Markov decision process for deep Q-learning model

As presented in the system model of mobile fog in Fig. 1, the mobile fogs are geographically distributed. The distributed fog network controller (FNC) or F-APC scavenging the available fog resources i.e. processing, memory, network to enable fog computation service. The randomness in the availability of resources and numerous options for allocating those resources for offloading computation fits the problem appropriate for modeling through Markov decision process (MDP) and solution through reinforcement learning.

According to the system model, three different sites are considered as feasible platform for offloading computation (1) the mobile fog in close proximity of end user devices, i.e. site $L_1$ (2) the adjacent mobile Fog (or distant mobile Fog) to handle mobility and load balancing issues, i.e. site $L_2$ (3) the remote public cloud to manage huge traffic and computing requirements and archiving, i.e. site $L_3$.

Intuitive, the deep Q-learning agent will find the best suitable place for offloading among the three feasible sites. Therefore, the possible action space $A$ of the learning agent can be defined as (1) $a_1$: offload in location $L_1$, (2) $a_2$: offload in location $L_2$ (3) $a_3$: offload in location $L_3$. The fog network controller (FNC) or F-APC decides the learning agent by moving the queueing model. In the learning agent, the consideration model is $M/M/c/K$, where $c$ is the number of servers in other fogs. The expected response time $E[T]$ of a fog node in $L_2$ can be determined through Eq. (10).

4.3. Reward function and deep Q-learning based computation offloading

The primary goal of the computation offloading is minimizing latency of processing each of the basic blocks, which mainly depends on the available processing and memory capability of a mobile fog node and the communication bandwidth. While the offloading request placed to the fog network controller (FNC), it should be on the request queue of the mobile fog. The FNC determines its processing capability by observing its state space and estimate the expected response time through queueing theoretic analysis.

To determine the estimated response time to process the basic block, the $M/M/1/K$ queueing model is considered. According to the queueing model each of the fog nodes has a single server, the maximum number of blocks it can process is $K$ including one under service, the arrival rate $\phi$ of processing request follows the Poisson distribution, and the service time $\mu$ follows the Exponential distribution i.e. inter-arrival and service time has memoryless property. Therefore, according to the queueing theory [3] the expected response time $E[T]$ of a fog node in $L_1$ is shown in (1).

$$E[T]_{L_1} = \frac{E[N]}{\phi (1 - P_k)} \quad (1)$$

Where, expected number of blocks on the fog node $E[N]$ and steady-state distribution or stationary probability of finding $K$ blocks on the queue $P_k$, and the probability of busy fog node $\rho$, and the probability of zero basic blocks on the queue $P_0$ can be defined as in the following Eqs. (2), (3), (4), and (5).

$$E[N] = \frac{\left( \frac{\rho}{\phi} \right) \left( 1 - (K + 1) \left( \frac{\rho}{\phi} \right)^K + K \left( \frac{\rho}{\phi} \right)^{K+1} \right)}{\left( 1 - \left( \frac{\rho}{\phi} \right) \right) \left( 1 - \left( \frac{\rho}{\phi} \right)^{K+1} \right)} \quad (2)$$

$$P_k = \frac{\rho^k}{\sum_{i=0}^{K} \rho^i}, \quad k = 0, \ldots, K \quad (3)$$

$$P_0 = 1 - \rho \quad (4)$$

$$\rho = \frac{\phi}{\mu} \quad (5)$$

If the learning agent considers to deploy a basic block in location $L_2$, that is in adjacent or remote mobile fog then the considered queueing model is $M/M/c/K$, where $c$ is the number of servers in other fogs. The expected response time $E[T]$ of a fog node in $L_2$ can be determined through (6).

$$E[T]_{L_2} = \frac{E[u] + \rho (1 - P_k)}{\phi (1 - P_k)} + I_{1,2} \quad (6)$$

Where, expected queue length $E[u]$ of a mobile fog in $L_2$, and steady-state distribution or stationary probability of finding $K$ blocks on the queue $P_k$, and the probability of busy fog node $\rho$, and the probability of zero basic blocks on the queue $P_0$ can be defined as in the following Eqs. (9), (7), (5), and (8). Here, $I_{1,2}$ is the communication latency between $L_1$ and $L_2$.

$$P_k = \left\{ \begin{array}{ll} \frac{\rho^c}{c! (1 - \left( \frac{\rho}{\phi} \right)^{K-c+1})} + \sum_{n=0}^{c-1} \frac{\rho^n n!}{c!}, & \text{if } \left( \frac{\rho}{\phi} \right) \neq 1 \\ \frac{\rho^c}{c! (K - c + 1) + \sum_{n=0}^{c-1} \rho^n n!}, & \text{if } \left( \frac{\rho}{\phi} \right) = 1 \end{array} \right. \quad (7)$$

$$P_0 = \left\{ \begin{array}{ll} \frac{P_0}{c! (1 - \left( \frac{\rho}{\phi} \right)^{K-c+1})} \left[ 1 - \left( \frac{\rho}{\phi} \right)^{K-c+1} \right], & \text{if } \left( \frac{\rho}{\phi} \right) \neq 1 \\ \frac{P_0}{(K - c + 1) \left( \frac{\rho}{\phi} \right)^{K-c}} \left[ 1 - \left( \frac{\rho}{\phi} \right)^{K-c} \right], & \text{if } \left( \frac{\rho}{\phi} \right) = 1 \end{array} \right. \quad (8)$$

If the learning agent considers to deploy a basic block in location $L_3$, that is in public cloud, the considered queueing model is $M/M/c/\infty$, where $c$ is the number of servers in public cloud, and unlimited buffer size. The expected response time $E[T]$ of a cloud node in $L_3$ can be determined through (10).

$$E[T]_{L_3} = \frac{1}{\mu} + \frac{1}{\mu (c - \rho)} \sum_{i=\infty}^{\infty} \frac{P_i}{c! (\rho)^i} + I_{1,3} \quad (10)$$

Where, the probability of zero basic blocks on the queue is $P_0$, and the utilization factor $\rho$, can be defined as in the following Eqs. (5) and (11). Here, $I_{1,3}$ is the communication latency between $L_1$ and $L_3$. 

$$E[T]_{L_3}$$

$$\frac{1}{\mu} + \frac{1}{\mu (c - \rho)} \sum_{i=\infty}^{\infty} \frac{P_i}{c! (\rho)^i} + I_{1,3} \quad (10)$$
\[ L_3, \]
\[ P_0 = \left( \sum_{i=0}^{c-1} \frac{\rho^i}{c! (1 - \frac{\rho}{c})} \right)^{-1} \]  

Thus, the estimated response time \( E_{ij} \) can be determined through (12).

\[ E_{ij} = \begin{cases} 
\frac{E[N]}{\phi (1 - P_k)}, & \text{if } i \in [1, 5, 7, 10] \text{ where } a_i \in A \text{ and } s_j \in S \\
\frac{E[N]}{\phi (1 - P_k)} + l_{i,2}; & \text{if } i \in [2, 4, 9] \text{ where } a_i \in A \text{ and } s_j \in S \\
\frac{1}{\mu} + \frac{1}{\mu (c - \rho)} \sum_{i=0}^{\infty} \frac{P_0}{c! (c^{k-i})} + l_{i,3}; & \text{if } i \in [3, 6, 8] \text{ where } a_i \in A \text{ and } s_j \in S 
\end{cases} \] 

While determining the response time of offloading computation in \( L_1, L_2 \) or \( L_3 \). The learning agent should learn where to offload for quicker response time. For every best placement i.e. offloading the agent is rewarded with \( R(s_i, a_i) \) as in (13).

\[ R(s_i, a_i) = \frac{E_{SLA}}{E_{ij}} - P_{SLA} \]  

(13)

\[ P_{SLA} = \begin{cases} 
E_{ij}; & \text{if } E_{ij} > E_{SLA} \\
0; & \text{otherwise} 
\end{cases} \]  

(14)

The learning agent will receive punishment \( P_{SLA} \) for the violation of service level agreement of response time as in (14), where \( E_{SLA} \) represents the threshold of response time as service level agreement.

To train the learning agent, the Q-learning approach is used, which is in the family of reinforcement learning. Therefore, the agent tries to explore the environment (here, the state space, \( S \)) and perform different actions from the action space \( A \) and observing the reward. As per the characteristics of reinforcement learning, in respect to the state space, the agent tries to perform the similar action if the agent receives reward and try to avoid those actions which causes it to pay penalty. The Q-learning worked as state–action pairs \( Q(s_i, a_i) \) and it learns optimal policy without knowing the internal probabilistic model. Then based on the learning i.e. based on the Q-table it can perform best action to the environment by using optimal policy. So, finding the optimal policy is the goal of the agent. However, optimal policy derived from Q-values, and therefore approximating Q-value is the key function of policy definition.

As the state space of computation offloading is vast. The possible combination of memory, CPU and bandwidth configuration are huge especially considering the fractional quantities. Therefore, the deep Q-learning model is applied to approximate Q-values and minimize the temporal difference \((T_d)\) in (15).

\[ T_d(a_i, s_i) = R(s_i, a_i) + \gamma \max_{a_{t+1}} Q(s_{t+1}, a_{t+1}) - Q(s_t, a_i) \]  

(15)

Where, \( R(s_i, a_i) \) is the reward for current action can be determined through (13); \( Q(s_i, a_i) \) is the current Q-value and \( Q(s_{t+1}, a_{t+1}) \) is the future Q-values with discount factor \( \gamma \). The applied deep Q-learning model is presented in Fig. 4.

5. Performance evaluation

The performance of proposed computation offloading in mobile Fog is evaluated through simulation study. In the simulation topology, two adjacent mobile Fogs are connected and each of mobile fog contains one FNC or F-APC and three F-AP Fog nodes. Both of the Fog nodes are connected to the cloud node with eight VMs. We mostly focus on two performance criteria: response time and energy consumption. The simulation parameters are presented in Table 2. The flow graph of our studied benchmark application i.e. N-queen problem is presented in Fig. 3. The resource usage history of the N-queen problem is also presented in Table 1, where the value of N is 4.

Fig. 5 shows that smart phone takes longer time to process the benchmark application, whereas the mobile fog takes shorter time to place the Queens on the board. The cloud also takes less time to process the solution because of the execution power of cloud servers. It shows that computation offloading is suitable for faster processing. Fig. 6 shows the energy consumption breakdowns of different computing environment. Without offloading the data the processor, display unit and other peripherals of smart phone consumes huge energy. That is, they consume much energy which may degrade the mobiles battery life. In contrast, cloud and fog can compute without display and with low power consumption unit. Fog consumes lowest energy because of the closest proximity of fog nodes reduce the radio energy consumption.

<table>
<thead>
<tr>
<th>Table 1</th>
<th>History of resource usages per basic block.</th>
</tr>
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<tbody>
<tr>
<td>Application ID</td>
<td>Method ID</td>
</tr>
<tr>
<td>A0001</td>
<td>M001</td>
</tr>
<tr>
<td>A0001</td>
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<td>M000</td>
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<td>M000</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Table 2</th>
<th>Simulation parameters of deep Q-learning based computation offloading.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sites</td>
<td>Parameters</td>
</tr>
<tr>
<td>Mobile stations</td>
<td>Total number</td>
</tr>
<tr>
<td>Memory per node</td>
<td>1 GB</td>
</tr>
<tr>
<td>Processor</td>
<td>1.6 GHz</td>
</tr>
<tr>
<td>Bandwidth</td>
<td>100 Mbps</td>
</tr>
<tr>
<td>Fog nodes</td>
<td>Total Number</td>
</tr>
<tr>
<td>Memory per node</td>
<td>16 GB</td>
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<tr>
<td>Processor</td>
<td>1.6 GHz</td>
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<tr>
<td>Bandwidth</td>
<td>1 Gbps</td>
</tr>
<tr>
<td>Average hops</td>
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</tr>
<tr>
<td>Cloud nodes</td>
<td>Total Number</td>
</tr>
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<td>Memory per VM</td>
<td>64 GB</td>
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<td>Processor</td>
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<td>Bandwidth</td>
<td>10 Gbps</td>
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<tr>
<td>Average hops</td>
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</tr>
</tbody>
</table>
Fig. 4. The deep Q-learning architecture for approximating Q updates.

Fig. 5. The log-normal response times of benchmark N-queen problem. We present the simulation results with 5 to 8 numbers of queens. Beyond 8 queens are not suitable to execute on smart phone because of longer execution time and up to 4 queens puzzle are not suitable for computation offloading because of low computational load.

Fig. 6. The log-normal energy consumptions of different computing models to generate outputs for different number of Queens of N-Queen puzzle.

The response time of remote cloud is always higher than the response time of mobile fog because mobile fog is nearer to the mobile stations and remote cloud is generally far from the mobile devices. Another important aspect of our proposed basic block offloading mechanism is the ability of parallel execution. ThinkAir

Fig. 7. Comparative study with existing benchmark solution of mobile cloud computing. ThinkAir deployed up to 8 colors to solve the 8-Queen problem, whereas Mobile Fog deployed 8 fog nodes to solve 8-Queen puzzle.

Fig. 8. Parallel execution of offloaded computation reduces the energy consumption both in ThinkAir and Mobile Fog computing.
the proposed deep Q-learning based code offloading method leverage the mobile cloud computing. As it is a multi-agent based distributed method, agents learn from the environment through reinforcements. The offloading method deploys basic blocks in compatible fog nodes to support parallelism. The experimental results show the improved performance of the proposed offloading method in respect to execution time and latency and energy consumption.

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### References


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